Research Article

Systems of Fuzzy Reasoning and Expert Knowledge-based Fuzzy Reasoning Systems, used in Modelling Real-world Phenomena

Andreea V Cojocaru and Stefan Balint*

Department of Computer Science, West University of Timisoara, 300223 Timisoara, Romania

Abstract

In this paper, the concept of 'system of fuzzy reasoning' is presented. It is the first temptation to expand ideas presented in [1] concerning 'human intelligence' linguistic variable and [2] concerning 'truth value of fuzzy reasoning' in the framework of the human intelligence linguistic variable. In 'systems of fuzzy reasoning', besides the 'human intelligence' linguistic variable also other linguistic variables are also used. An expert knowledge-based system of fuzzy reasoning describing the dynamics of a real-world phenomenon is presented.

1. Introduction

Systems of fuzzy reasoning provide a theoretical framework for modelling. First, by defining the concept of system of fuzzy reasoning, its properties, and then by stating the necessary and sufficient conditions to encompass all possible 'If...THEN ...' statements. Finally, selecting the resulting membership function [3]. pg.81. More statements that are general can be formulated on a system of reasoning than on arbitrary ones. Linguistic variables can often be used to transform non-numerical reasoning premises and responses into a numerical form.

Definition 1.1

A system of fuzzy reasoning $R = \{R_1, R_2, \dots, R_I\}$ is a set of fuzzy reasonings R_i

$$R_i = If(a_1 \text{ is } A_{i1}) \bowtie_1^i (a_2 \text{ is } A_{i2}) \bowtie_{k-1}^i (a_k \text{ is } A_{ik}) \text{ then } (b_i \text{ is } B_i)$$

where:

 $i = 1, ..., I, k = 1, ..., K, A_{ik}$ and B_i are triangular or trapezoidal fuzzy subsets of the set of real numbers \mathbb{R}^1 .

The symbols denoted by $(a_1 is A_{i1}), (a_2 is A_{i2}), ..., (a_k is A_{ik})$ are fuzzy statements (called by some people arguments), the symbols $a_1, a_2, ..., a_k$ are real numbers and are called premises. The symbols denoted by $(b_i is B_i)$ are fuzzy statements, called individual consequences or responses. The symbols b_i are real numbers. The membership functions of the fuzzy subsets A_{ik} and B_i are denoted by $f_{A_{ik}}$ and f_{B_i} respectively. The symbol denoted by \bowtie_i is one of the fuzzy logic operators: *NOT, AND, OR, XOR.*

According to [2], the part of the fuzzy logic reasoning R_i (see formula (1.1)) denoted by

$$(a_1 \text{ is } A_{i1}) \bowtie_1^i (a_2 \text{ is } A_{i2}) \bowtie_2^i \dots \bowtie_{k-1}^i (a_k \text{ is } A_{ik})$$

is called a fuzzy logic expression of R_i .

Remark that, according to this definition, the number of arguments can be different for different logical expressions of the

More Information

*Address for correspondence: Stefan Balint, Department of Computer Science, West University of Timisoara, 300223 Timisoara, Romania, Email: stefan.balint@e-uvt.ro

Submitted: June 09, 2025 **Approved:** June 16, 2025 **Published:** June 17, 2025

How to cite this article: Cojocaru AV, Balint S. Systems of Fuzzy Reasoning and Expert Knowledge-based Fuzzy Reasoning Systems, used in Modelling Real-world Phenomena. Int J Phys Res Appl. 2025; 8(6): 156-168. Available from: https://dx.doi.org/10.29328/journal.ijpra.1001124

Copyright license: © 2025 Cojocaru AV, et al. This is an open access article distributed under the Creative Commons Attribution License, which permits unrestricted use, distribution, and reproduction in any medium, provided the original work is properly cited.

Keywords: Linguistic variable; The true value in a fuzzy reasoning system; Expert knowledgebased systems of fuzzy reasoning



OPEN ACCESS

(1.1)

(1.2)



system. Concerning this aspect, we point out that it is possible to formulate all reasoning with a common number *K* of arguments by taking for arguments *k*, which are not used in rule *i*, the membership function $f_{A_{i,k}}(x) = 1$ for all $x \in \mathbb{R}^1$.

To calculate the response of a fuzzy reasoning system = { R_1 , R_2 , ..., R_i }, the truth value of reasoning R_i (degree of fulfillment $DOF(R_i)$) has to be evaluated using a selected inference method. In the next step, the responses of the individual's reasoning are combined with the help of a combination method. Finally, a defuzzification method transforms the fuzzy reasoning system's response to a crisp result. This procedure can be considered as the definition of a function assigning the final (crisp) result to the input.

The subject of the truth value DOF() of a fuzzy logic reasoning R_i

$$R_{i} = If(a_{1} \text{ is } A_{i1}) \bowtie_{1}^{i} (a_{2} \text{ is } A_{i2}) \bowtie_{2}^{i} \dots \bowtie_{k-1}^{i} (a_{k} \text{ is } A_{ik}) \text{ then } (b_{i} \text{ is } B_{i})$$

is largely discussed in [2], in the framework of the 'human intelligence' linguistic variable.

In the following, we expand the truth value computation for a system of fuzzy logic reasoning by using several illustrative examples of such computation.

Example 1.1 (system of two reasonings with one premise) Consider the fuzzy reasoning system *R* consisting of two reasonings $R = \{R_1, R_2\}$ and one premise a_1 . The reasons are given by

$$R_{1} = If(a_{1}isA_{11})then(b_{1}isB_{1}), A_{11} = (1,2,3), B_{1} = (1,2,3) triangular fuzzy subsets$$

 $R_2 = If(a_1 is A_{21}) then(b_2 is B_2), A_{21} = (2,3,4), B_2(3,4,5) triangular fuzzy subsets$

In case of the fuzzy reasoning R_1 , the logical expression is the statement $(a_1 ext{ is } A_{11})$ whose truth value is

$$f_{A_{11}}(a_1) = a_1 - 1 \text{ for } 1 < a_1 < 2 \text{ and } f_{A_{11}}(a_1) = 3 - a_1 \text{ for } 2 < a_1 < 3.$$

In case of the fuzzy reasoning R_2 , the logical expression is the statement $(a_1 ext{ is } A_{21})$ whose truth value is

$$f_{A_{21}}(a_1) = a_1 - 2 \text{ for } 2 < a_1 < 3 \text{ and } f_{A_{21}}(a_1) = 4 - a_1 \text{ for } 3 < a_1 < 4.$$

The normed weighted sum of a combination of individual responses (*DOF*, B_i) is the overall fuzzy consequence *B* with the membership function [2] pg.086.

$$f_B(x) = \frac{\sum_{i=1}^{2} DOF(R_i(a_1)) \times \beta_i \times f_{B_i}(x)}{\max_u [\sum_{i=1}^{2} DOF(R_i(a_1)) \times \beta_i \times f_{B_i}(u)]}$$
(1.3)

where
$$\beta_i = \frac{1}{\int_{-\infty}^{\infty} f_{B_i}(x) dx}$$
.

Computing
$$\beta_i$$
, we find $_1 = \beta_2 = 1$. Hence $f_B(x) = \frac{f_{A_{11}}(a_1) \times f_{B_1}(x) + f_{A_{21}}(a_1) \times f_{B_2}(x)}{max_u [f_{A_{11}}(a_1) \times f_{B_1}(u) + f_{A_{21}}(a_1) \times f_{B_2}(u)]}$.

For $1 < a_1 < 2$ after replacing $f_{A_{11}}(a_1), f_{A_{21}}(a_1)$ the following result is found:

$$\begin{split} f_B(x) &= \frac{(a_1 - 1) \times f_{B_1}(x) + 0 \times f_{B_2}(x)}{max_u[(a_1 - 1) \times f_{B_1}(u) + 0 \times f_{B_2}(u)]} = \frac{(a_1 - 1) \times (x - 1)}{max_u[(a_1 - 1) \times f_{B_1}(u)]} = x - 1 \text{ for } 1 < x < 2 \\ f_B(x) &= \frac{(a_1 - 1) \times f_{B_1}(x) + 0 \times f_{B_2}(x)}{max_u[(a_1 - 1) \times f_{B_1}(u) + 0 \times f_{B_2}(u)]} = \frac{(a_1 - 1) \times (3 - x)}{max_u[(a_1 - 1) \times f_{B_1}(u)]} = 3 - x \text{ for } 2 < x < 3 \\ f_B(x) &= \frac{(a_1 - 1) \times f_{B_1}(x) + 0 \times f_{B_2}(x)}{max_u\left[(a_1 - 1) \times f_{B_1}(u) + 0 \times f_{B_2}(u)\right]} = \frac{0}{max_u\left[(a_1 - 1) \times f_{B_1}(u)\right]} = 0 \text{ for } 3 < x < 4 \end{split}$$



$$f_{B}(x) = \frac{(a_{1}-1) \times f_{B_{1}}(x) + 0 \times f_{B_{2}}(x)}{max_{u} \left[(a_{1}-1) \times f_{B_{1}}(u) + 0 \times f_{B_{2}}(u)\right]} = \frac{0}{max_{u} \left[(a_{1}-1) \times f_{B_{1}}(u)\right]} = 0 \text{ for } 4 < x < 5$$

According to [2] p. 086. The membership function $f_B(x)$ of the overall fuzzy consequence *B* for $1 < a_1 < 3$ is the fuzzy subset represented in the next Figure 1.1:



The fuzzy mean of the overall fuzzy consequence B, denoted by M(B), and defined by

$$M(B) = \frac{\int_{-\infty}^{\infty} x \times f_B(x) dx}{\int_{-\infty}^{\infty} f_B(x) dx}$$
(1.4)

is the location of the overall fuzzy consequence *B*. It is also called the center of gravity or centroid. This is the number for which the part of the membership function $f_B(x)$ on the left of this number is in equilibrium with the right side. The equilibria occur when the moments corresponding to the two sides are equal. Computing the fuzzy mean directly by using formula (1.4), the following result is found: M(B) = 2. Therefore, the equilibrium in the case of this example is situated at the point x = 2.

On the other hand, according to [2], when the normed weighted sum combination and mean defuzzification are used, the following equality holds:

$$R(a_1) = M(B)(a_1) = \frac{\sum_{i=1}^{2} d_i \times M(B_i)}{\sum_{i=1}^{2} d_i}$$
(1.5)

Where d_1 , d_2 are the truth values of the logical expression of the fuzzy reasoning R_1 , R_2 , respectively, and $M(B_1)$, $M(B_2)$ are the mean value of the individual answers of the fuzzy reasoning R_1 , R_2 , respectively. In case of the system of fuzzy reasoning $R = \{R_1, R_2\}$

For $1 < a_1 < 2$, the following equality holds:

$$d_1 = a_1 - 1, d_2 = 0, M(B_1) = 2 M(B_2) = 4$$

Replacing these values in formula (1.5), it follows that $R(a_1) = M(B)(a_1) = \frac{(a_1-1)\times 2 + 0\times 4}{a_1-1+0} = 2.$

Remark that the localization of equilibrium obtained with (1.5) is the same as that obtained with (1.4) via membership function.

For
$$2 < a_1 < 3$$
, $d_1 = 3 - a_1$, $d_2 = a_1 - 2$, $M(B_1) = 2$, $M(B_2) = 4$. Replacing these values in formula (1.5), the following result is found:
 $R(a_1) = M(B)(a_1) = \frac{(3 - a_1) \times 2 + (a_1 - 2) \times 4}{3 - a_1 + a_1 - 2} = 2 \times a_1 - 2.$



Therefore, when $2 < a_1 < 3$, the equilibrium is located at the point $x = 2 \times a_1 - 2$.

For $3 < a_1 < 4$, $d_1 = 0$, $d_2 = 4 - a_1$, $M(B_1) = 2$, $M(B_2) = 4$. Replacing these values in formula (1.5), the following result is found: $R(a_1) = M(B)(a_1) = \frac{0 \times 2 + (4 - a_1) \times 4}{0 + 4 - a_1} = 4$.

Therefore, when $3 < a_1 < 4$, the equilibrium is located at the point x = 4.

The number $R(a_1) = M(B)(a_1)$, assigning the final (crisp) result to the input a_1 , is considered the location of the truth value of the system of fuzzy reasoning $R = \{R_1, R_2\}$ corresponding to the input a_1 . The graphic of the function $R(a_1) = M(B)(a_1)$ is presented in the next Figure 1.2:

Figure 1.2. Show that: for one input $a_1 \in [1,2]$ the truth value of the overall response of system is located at 2, for one input $a_1 \in [2,3]$ the truth value of the overall response of system is located at $2a_1 - 2$, for one input $a_1 \in [3,4]$ the truth value of the overall response of system is located at 4. It can be seen that the centroid is constant if a small perturbation of the input $a_1 \in (1,2) \cup (3,4)$ occurs. For input $a_1 \in [2,3]$, the truth value location of the overall response of the system increases linearly from 2 to 4. This interval is more appropriate to control the equilibrium location via the premise a_1 .



Example 1.2. (Example 4.4. Pg. 90. [1], system of three reasonings with one premise. Consider the fuzzy reasoning system *R* consisting of the following three fuzzy reasonings, $R = \{R_1, R_2, R_3\}$:

$$R_1$$
 is $If(ais A_1)$ then $(b_1 is B_1), A_1 = (1, 2, 3), B_1 = (0, 1, 2)$ triangular fuzzy subsets

$$R_2$$
 is If $(a i s A_2)$ then $(b_2 i s B_2)$, $A_2 = (3,4,5)$, $B_2 = (2,3,4)$ triangular fuzzy subsets

 R_3 If $(a i s A_3)$ then $(b_3 i s B_3)$, $A_3 = (0,3,6,)$, $B_3 = (0,2,4)$ triangular fuzzy subsets

The truth values of fuzzy logic expressions of reasoning are:

$$DOFR_1(a) = a - 1$$
, for $1 < a < 2$; $DOFR_1(a) = 3 - a$ for $2 < a < 3$

$$DOFR_2(a) = a - 3$$
, for $3 < a < 4$; $DOFR_2(a) = 5 - a$ for $4 < a < 5$

$$DOFR_3(a) = \frac{a}{3}$$
, for $0 < a < 3$; $DOFR_3(a) = \frac{6-a}{3}$ for $3 < a < 6$

On the interval [1,5], the $DOFR_i(a)$ can be written as

for
$$1 < a < 2$$
; $DOFR_1(a) = a - 1$, $DOFR_2(a) = 0$; $DOFR_3(a) = \frac{a}{3}$;

for 2 < a < 3;
$$DOFR_1(a) = 3 - a$$
, $DOFR_2(a) = 0$; $DOFR_3(a) = \frac{a}{3}$;



for 3 < a < 4;
$$DOFR_1(a) = 0$$
, $DOFR_2(a) = a - 3$; $DOFR_3(a) = \frac{6 - a}{3}$;
for 4 < a < 5; $DOFR_1(a) = 0$, $DOFR_2(a) = 5 - a$; $DOFR_3(a) = \frac{6 - a}{3}$;

On the other hand:

$$\begin{split} f_{B_1}(b_1) &= b_1; \quad \text{for } 0 < b_1 < 1 \quad f_{B_1}(b_1) = 2 - b_1; \text{ for } 1 < b_1 < 2 \\ f_{B_2}(b_2) &= b_2 - 2; \text{ for } 2 < b_2 < 3 \quad f_{B_2}(b_2) = 4 - b_2; \text{ for } 3 < b_2 < 4 \\ f_{B_2}(b_3) &= \frac{b_2}{2}; \quad \text{for } 0 < b_3 < 2 \quad f_{B_3}(b_3) = \frac{4 - b_2}{2}; \text{ for } 2 < b_3 < 4 \end{split}$$

Therefore, considering the normed weighted sum combination with mean defuzzification, the resulting overall consequence location of the fuzzy reasoning system $R = \{R_1, R_2, R_3\}$: is defined as the following one variable function R(a) = M(B)(a) (relation 3.3.5 pg.73 [1]:

$$R(a) = \frac{1 \times DOFR_1(a) + 3 \times DOFR_2(a) + 2 \times DOFR_3(a)}{DOFR_1(a) + DOFR_2(a) + DOFR_3(a)}$$
(1.5)

Hence, we obtain:

for
$$1 < a < 2$$
 $R(a) = \frac{1 \times (a-1) + 3 \times 0 + 2 \times \frac{a}{3}}{a-1+0+\frac{a}{3}} = \frac{5 \times a-3}{4 \times a-3}$
for $2 < a < 3$ $R(a) = \frac{1 \times (3-a) + 3 \times 0 + 2 \times \frac{a}{3}}{3-a+0+\frac{a}{3}} = \frac{9-a}{9-2 \times a}$
for $3 < a < 4$ $R(a) = \frac{1 \times 0 + 3 \times (a-3) + 2 \times \frac{6-a}{3}}{0+a-3+\frac{6-a}{3}} = \frac{7 \times a-15}{2 \times a-3}$
for $4 < a < 5$ $R(a) = \frac{1 \times 0 + 3 \times (5-a) + 2 \times \frac{6-a}{3}}{0+5-a+\frac{6-a}{3}} = \frac{57-11 \times a}{21-4 \times a}$

The graphic of the one variable function R(a) = M(B)(a) for $a \in A$ is represented in the next Figure 1.3:





Example 1.3 (system of two reasonings with two premises) Consider the fuzzy reasoning system *R* consisting of two reasonings $R = \{R_1, R_2\}$ where the reasonings are given by:

$$\begin{aligned} &R_{1} If (a_{1}is A_{11}) then (b_{1}is B_{1}), A_{11} = (1,2,3), B_{1} = (1,2,3) triangular fuzzy subsets \\ &R_{2} If (a_{2}is A_{22}) then (b_{2}is B_{2}), A_{22} = (2,3,4), B_{2} = (3,4,5) triangular fuzzy subsets \\ &DOFR_{1} (a_{1}) = a_{1} - 1 \text{ for } 1 < a_{1} < 2; DOFR_{1} (a_{1}) = 3 - a_{1} \text{ for } 2 < a_{1} < 3 \\ &DOFR_{1} (a_{2}) = a_{2} - 2 \text{ for } 2 < a_{2} < 3; DOFR_{2} (a_{2}) = 4 - a_{2} \text{ for } 3 < a_{2} < 4 \\ &f_{B_{1}} (b_{1}) = b_{1} \quad \text{ for } 1 < b_{1} < 2 \quad f_{B_{1}} (b_{1}) = 3 - b_{1} \text{ for } 2 < b_{1} < 3 \\ &f_{B2} (b_{2}) = b_{2} \quad \text{ for } 3 < b_{2} < 4 \quad f_{B_{2}} (b_{2}) = 5 - b_{2} \text{ for } 4 < b_{2} < 5 \end{aligned}$$

For the maximum combination B of B_1, B_2 [2] pg.0.84, the membership function of the overall response is:

$$f_{B}(b) = \max\{DOFR_{1}(a_{1}) \times f_{B_{1}}(b), DOFR_{2}(a_{2}) \times f_{B_{2}}(b)\} =$$

$$= \max\{DOFR_{1}(a_{1}) \times (b-1), DOFR_{2}(a_{2}) \times 0\} =$$

$$= DOFR_{1}(a_{1}) \times (b-1) \text{ for } 1 < b < 2$$

$$f_{B}(b) = \sum_{a_{1} < b_{1} < b_{2} <$$

 $f_B(b) = \max\{DOFR_1(a_1) \times f_{B_1}(b), DOFR_2(a_2) \times f_{B_2}(b)\} = \\ = \max\{DOFR_1(a_1) \times (3-b), DOFR_2(a_2) \times 0\} = \\ = DOFR_1(a_1) \times (3-b) \text{ for } 2 < b < 3$

$$\begin{split} f_B(b) &= \max\{DOFR_1(a_1) \times f_{B_1}(b), \ DOFR_2(a_2) \times f_{B_2}(b)\} = \\ &= \max\{DOFR_1(a_1) \times 0, \ DOFR_2(a_2) \times (b-3)\} = \\ &= DOFR_2(a_2) \times (b-3) \ \text{for } 3 < b < 4 \end{split}$$

$$\begin{split} f_B(b) &= \max\{DOFR_1(a_1) \times f_{B_1}(b), \ DOFR_2(a_2) \times f_{B_2}(b)\} = \\ &= \max\{DOFR_1(a_1) \times 0, \ DOFR_2(a_2) \times (5-b)\} = \\ &= DOFR_2(a_2) \times (5-b) \ \text{for } 4{<}b{<}5 \end{split}$$

The mean value $M(B)(a_1,a_2)$ (centroid or center of gravity) of the defuzzified consequence *B*, denoted by $R(a_1,a_2)$, is used in multiplicative or additive form for the location of the truth value of the fuzzy reasoning system. In this case, it is:

$$R(a_1, a_2) = DOFR_1(a_1) + 2 \times DOFR_2(a_2) = (a_1 - 1) + 2 \times DOFR_2(a_2) for 1 < a_1 < 2$$

and

$$R(a_1, a_2) = DOFR_1(a_1) + 2 \times DOFR_2(a_2) = (3 - a_1) + 2 \times DOFR_2(a_2) \text{ for } 2 < a_1 < 3.$$

Therefore:

 $R(a_{1},a_{2}) = (a_{1}-1) + 2 \times (a_{2}-2) \text{ for } 1 < a_{1} < 2 \text{ and } 2 < a_{2} < 3$ $R(a_{1},a_{2}) = (a_{1}-1) + 2 \times (4-a_{2}) \text{ for } 1 < a_{1} < 2 \text{ and } 3 < a_{2} < 4$ $R(a_{1},a_{2}) = (3-a_{1}) + 2 \times (a_{2}-2) \text{ for } 2 < a_{1} < 3 \text{ and } 2 < a_{2} < 3$ $R(a_{1},a_{2}) = (3-a_{1}) + 2 \times (4-a_{2}) \text{ for } 2 < a_{1} < 3 \text{ and } 3 < a_{2} < 4$

The location $R(a_1, a_2)$, of the truth value of the fuzzy reasoning system in the case of the overall answer is presented in the next Figure 1.4:





Other combinations can also be used. Using, for example, normed weighted sum combination and mean defuzzification, the overall response location can be obtained directly by using the formula:

$$R(a_1, a_2) = M(B)(a_1, a_2) = \frac{\sum_{i=1}^2 d_i \times M(B_i)}{\sum_{i=1}^2 d_i}$$
(1.6)

Where d_1 , d_2 are the truth values of the logical expression of the fuzzy reasoning R_1 , R_2 , respectively, and $M(B_1)$, $M(B_2)$ are the mean value of the individual answers of the fuzzy reasoning R_1 , R_2 , respectively. In case of the same system of reasoning

1

$$\begin{aligned} R_1 & If (a_1 is A_{11}) then (b_1 is B_1), A_{11} = (1, 2, 3), B_1 = (1, 2, 3) triangular fuzzy subsets \\ R_2 & If (a_2 is A_{22}) then (b_2 is B_2), A_{22} = (2, 3, 4), B_2 = (3, 4, 5) triangular fuzzy subsets \end{aligned}$$

Using the already computed truth values

$$d_{1} = DOFR_{1}(a_{1}) = a_{1} - 1 \text{ for } 1 < a_{1} < 2; DOFR_{1}(a_{1}) = 3 - a_{1} \text{ for } 2 < a_{1} < 3$$
$$d_{2} = DOFR_{2}(a_{2}) = a_{2} - 2 \text{ for } 2 < a_{2} < 3; DOFR_{2}(a_{2}) = 4 - a_{2} \text{ for } 3 < a_{2} < 4$$

and the values of $M(B_1) = 2$, $M(B_2) = 4$ computed using formula

$$M(B_i) = \frac{\int_{-\infty}^{\infty} x \times f_{B_i}(x) dx}{\int_{-\infty}^{\infty} f_{B_i}(x) dx} \quad i = 1,2$$
(1.7)

and replacing in (1.6), for the overall responses $R(a_1, a_2) = M(B)(a_1, a_2)$, the following result is found:

$$R(a_{1},a_{2}) = \frac{2 \times (a_{1}-1) + 4 \times (a_{2}-2)}{a_{1}+a_{2}-3} = \frac{2 \times a_{1}+4 \times a_{2}-10}{a_{1}+a_{2}-3} \text{ for } 1 < a_{1} < 2 \text{ and } 2 < a_{2} < 3$$

$$R(a_{1},a_{2}) = \frac{2 \times (a_{1}-1) + 4 \times (4-a_{2})}{a_{1}-a_{2}+3} = \frac{2 \times a_{1}-16 \times a_{2}+14}{a_{1}-a_{2}+3} \text{ for } 1 < a_{1} < 2 \text{ and } 3 < a_{2} < 4$$

$$R(a_{1},a_{2}) = \frac{2 \times (3-a_{1}) + 4 \times (a_{2}-2)}{-a_{1}+a_{2}+1} = \frac{-2 \times a_{1}+4 \times a_{2}-2}{-a_{1}+a_{2}+1} \text{ for } 2 < a_{1} < 3 \text{ and } 2 < a_{2} < 3$$

$$R(a_{1},a_{2}) = \frac{2 \times (3-a_{1}) + 4 \times (4-a_{2})}{-a_{1}-a_{2}+7} = \frac{-2 \times a_{1}-4 \times a_{2}+22}{-a_{1}-a_{2}+7} \text{ for } 2 < a_{1} < 3 \text{ and } 3 < a_{2} < 4$$

$$(1.8)$$



2. What is a complete and what does redundant system of fuzzy reasoning?

A system of fuzzy reasoning is complete or consistent on a set of premises *A* if it can provide an answer to all possible questions concerning the phenomenon modeled, see[3], pg.82. More precisely:

Definition 2.1. The system of fuzzy reasoning

$$R=\{R_1,R_2,\ldots R_1\},\$$

is complete on the set of premises A if for every premise $(a_1, a_2, \dots, a_K) \in A$ the corresponding and the combined response set $B(a_1, a_2, \dots, a_K)$ is a nonempty fuzzy set.

Note that the definition requires not only that for every premise $(a_1, a_2, \dots, a_K) \in A$ there should be a reasoning *i* with a nonempty response, but it also requires the combined response to be non-empty. The completeness of a system of fuzzy reasoning depends on the set of premises *A* on which the reasoning system's responses are to be found, and on the combination method used. The defuzzification does not influence the completeness of the reasoning system. The minimum combination seeks the difficult task of finding complete agreement, while the other methods only exclude responses that are impossible for each rule. Therefore, it is not surprising that the condition of completeness is easier to fulfill using the maximum or additive combination methods than using the minimum one. For a system of fuzzy reasoning, the following statements can be formulated regarding completeness.

Statement 2.1. [3]. pg.83. The fuzzy reasoning system $R = \{R_1, R_2, ..., R_i\}$, used with maximum or additive combination method is complete on the premises set *A* if and only if for each premise $(a_1, a_2, ..., a_K) \in A$ there is a reasoning R_i such that $DOF(R_i)(a_1, a_2, ..., a_K) > 0$.

Statement 2.2. [3]. pg.83. The system of fuzzy reasoning $R = \{R_1, R_2, ..., R_1\}$, used with the minimum combination method, is complete on the premises set *A* if and only if

1. for each premise $(a_1, a_2, \dots, a_K) \in A$ there is a reasoning R_i such that $DOF(R_i)(a_1, a_2, \dots, a_K) > 0$

and

2. For any couple of two rules R_i and R_j if there is $(a_1, a_2, \dots, a_K) \in A$ such that $DOF(R_i)(a_1, a_2, \dots, a_K) > 0$ and $DOF(R_j)(a_1, a_2, \dots, a_K) > 0$, then $B_i \cap B_j \neq \emptyset$.

If the minimum combination is used, then the fuzzy reasoning system considered in Example 1.3 is not complete on the interval A = [2,3]. That is because for any $a_1 \in A$ the equality $\min \left\{ f_{B_1}(a_1), f_{B_2}(a_1) \right\} = 0$ hold.

If the maximum combination or additive combination is used, then the fuzzy reasoning system considered in Example 1.3 is complete on the interval A = [2,3].

The completeness of a system of fuzzy reasoning used with maximum or additive combinations depends only on the 'range' on which the arguments are defined. This 'range', which is called the support of a system of fuzzy reasoning, is defined as follows:

Definition 2.3. The support of the fuzzy reasoning

 $R_i = If(a_1 \text{ is } A_{i1}) \bowtie_1^i (a_2 \text{ is } A_{i2}) \bowtie_2^i \dots \bowtie_{k-1}^i (a_k \text{ is } A_{ik}) \text{ then } (b_i \text{ is } B_i)$

Is the *K* - *dimesional* set defined by

 $supp(R_i) = supp(A_{i1}) \times \dots \times supp(A_{iK})$

Statement 2.3. [3].pg.84.The system of fuzzy reasoning $R = \{R_1, R_2, ..., R_1\}$, used with maximum or additive combinations, is complete on *A* if and only if

$$A \subset \bigcup_{i=1}^{i=I} supp(R_i).$$

Statement 2.4. .[3].pg.86.The system of fuzzy reasoning $R = \{R_1, R_2, ..., R_i\}$, used with maximum or additive combinations is complete on $A = \bigcup_{i=1}^{i=I} supp(R_i)$.

The overlap between the premises is an important property of fuzzy reasoning systems. It thus seems that general fuzzy reasoning systems may be at least partly redundant. However, this is not true: even reasoning whose premises are completely



covered by other reasoning might still modify the consequences. Therefore, the possibility of removing fuzzy reasoning from a general fuzzy reasoning system without a major change in the consequence cannot be judged based on only the premises. It should be done by comparing the response set. In order to know which fuzzy rules can be removed, a measure of the overlap was defined. For more details, see [1]. Pg. 87. In the following, we intend to give an illustrative example concerning what happens if a fuzzy rule is removed.

Example 2.1. ([3].86). Consider the general fuzzy reasoning system *R* consisting of three reasoning $R = \{R_1, R_2, R_3\}$ where the reasoning is given by:

$$\begin{aligned} R_{1} &= If \left(a_{1} is A_{11} \right) then \left(b_{1} is B_{1} \right), A_{11} = (1,2,3), B_{1} = (0,2,4) \ triangular \ fuzzy \ subsets \\ R_{2} &= If \left(a_{1} is A_{21} \right) then \left(b_{2} \ is B_{2} \right), A_{21} = (2,3,4), B_{1} = (3,5,7) \ triangular \ fuzzy \ subsets \\ R_{3} &= If \left(a_{1} is A_{31} \right) then \left(b_{3} \ is B_{3} \right), A_{31} = (1.5,2.5,3.5), B_{3} = (1,3,5) \ triangular \ fuzzy \ subsets \end{aligned}$$

The premise of the third reasoning is fully covered by the premises of the other two reasonings. The fuzzy reasoning system would remain complete (even for the minimum combination) on A = [1.5, 2.5] if the third rule were removed. On the other hand, the consequence of using mean defuzzification and additive combination with

 $a_1 = 2.5 leads to 3.25 and removing R_3 gives 3.5$

3. Expert knowledge-based system of fuzzy reasoning

Assessment of fuzzy reasoning is a procedure where knowledge and / or available data are translated or encoded in fuzzy reasoning. Since fuzzy reasoning system responses both on the combination and defuzzification method applied, this choice has to be taken into account in the assessment.

According to [3], at least four different ways to assess a fuzzy reasoning system may be distinguished:

- a) The fuzzy reasoning system is known by the experts and can be defined directly.
- b) The fuzzy reasoning system can be assessed by experts directly, but available data should be used to update it.
- c) The fuzzy reasoning system is not known explicitly, but the variables required for the description of the system can be specified by experts.
- d) Only a set of observations is available, and a fuzzy reasoning system has to be constructed to describe the interconnection between the input/output elements of the data set.

In this section, we will provide a system of fuzzy reasoning based on expert knowledge.

Consider algae growth in a water body receiving a steady loading of nutrients, including dissolved oxygen. It has been observed that available nutrients *x* and algae biomass *y* vary in time and oscillate. Let *x* and *y* be measured on the scale between 0 and 1. For the fuzzy reasoning construction, let only two state descriptors, high *h* and low *l*, be used. For describing the process in terms of a system of fuzzy reasoning, let us consider the expert knowledge incorporated in the following two triangular fuzzy numbers defined on the unit interval [0,1]:

$$A_h = (0.4, 0.9, 1) \quad A_l = (0, 0.1, 0.7)$$
 (3.1)

With respect means:

$$M(A_h) = \frac{2.3}{3} = 0.76 \quad M(A_l) = \frac{0.8}{3} = 0.27 \tag{3.2}$$

According to experts, the transitions between the states can be described as: starting with states $hh = (xisA_h)AND(yisA_h)$ at moment *t*, the level of available nutrients and algae is *h*. In the next time of period (let say 1 unit) the following process take place: algae reduce nutrients to $states lh = (xisA_l)AND(yisA_h)$; in turn because nutrients are insufficient algae become $l states ll = (xisA_l)AND(yisA_l)$; the nutrients are replenished and become $h state hl = (xisA_h)AND(yisA_l)$; in the next period again algae become $h state hh = (xisA_h)AND(yisA_h)$. Schematically: Systems of Fuzzy Reasoning and Expert Knowledge-based Fuzzy Reasoning Systems, used in Modelling Real-world Phenomena

$$hh \rightarrow lh \rightarrow ll \rightarrow hl \rightarrow hh$$

`

This description is fuzzy, and to describe the process in terms of a system of fuzzy reasoning, let us consider the following system of fuzzy reasoning:

$$R_{hh} is If (xisA_{h})AND(yisA_{h})then(xisA_{l})AND(yisA_{h})$$

$$R_{lh} is If (xisA_{l})AND(yisA_{h})then(xisA_{l})AND(yisA_{l})$$

$$R_{ll} is If (xisA_{l})AND(yisA_{l})then(xisA_{h})AND(yisA_{l})$$

$$R_{hl} is If (xisA_{h})AND(yisA_{l})then(xisA_{h})AND(yisA_{h})$$
(3.4)

The system of fuzzy reasoning (3.4) is an algae growth model and can be used to construct the state vector trajectory in a continuous space for a given initial state (x(0), y(0)). This trajectory is unique.

To illustrate the above proposition, consider the mean defuzzification and the normed weighted sum combination method

$$R(a) = \frac{\sum_{i=1}^{4} M(B_i) \times DOF(R_i(a))}{\sum_{i=1}^{4} DOF(R_i(a))}$$
(3.5)

Since in all reasoning the product fuzzy logic operator AND is used in formula (3.5), we replace:

$$DOFR_{1}(a) = DOFR_{1}(x, y) = (DOF((xisA_{h})AND(yisA_{h}))) = f_{A_{h}}(x) \times f_{A_{h}}(y),$$

$$DOFR_{2}(a) = DOFR_{2}(x, y) = DOF((xisA_{l})AND(yisA_{h})) = f_{A_{l}}(x) \times f_{A_{h}}(y),$$

$$DOFR_{3}(a) = DOFR_{3}(x, y) = DOF((xisA_{l})AND(yisA_{l})) = f_{A_{l}}(x) \times f_{A_{l}}(y),$$

$$DOFR_{4}(a) = DOFR_{4}(x, y) = DOF((xisA_{h})AND(yisA_{l})) = f_{A_{h}}(x) \times f_{A_{l}}(y);$$
(3.6)

Remark that he membership functions $f_{A_{h}}(x)$ and $f_{A_{l}}(x)$ are given:

$$f_{A_{h}}(x) = 0 \text{ for } x < 0.4, f_{A_{h}}(x) = \frac{x - 0.4}{0.5} \text{ for } 0.4 < x < 0.9, f_{A_{h}}(x) = \frac{1 - x}{0.1} \text{ for } 0.9 < x < 1$$

$$f_{A_{h}}(x) = 0 \text{ for } 1 < x$$

$$(3.7)$$

$$f_{A_{l}}(x) = 0 \text{ for } x < 0, f_{A_{l}}(x) = \frac{x}{0.1} \text{ for } 0 < x < 0.1, f_{A_{l}}(x) = \frac{0.7 - x}{0.6} \text{ for } 0.1 < x < 0.7$$

$$f_{A_{l}}(x) = 0 \text{ for } 0.7 < x \tag{3.8}$$

For the initial state x = 0.5, y = 0.6 the membership values are:

And the *DOF* - *s* values appearing in (3.6) are :

In case of nutrients x, the mean values $M(B_i)$ of individual consequences are replaced by

$$M(B_1) = M(A_l) = 0.27, M(B_2) = M(A_l) = 0.27,$$

$$M(B_3) = M(A_h) = 0.76, M(B_4) = M(A_h) = 0.76$$
(3.10)



(3.3)



In case of algae y, the mean values $M(B_i)$ of individual consequences are replaced by

$$M(B_{1}) = M(A_{h}) = 0.76, (B_{2}) = M(A_{l}) = 0.27,$$

$$M(B_{3}) = M(A_{l}) = 0.27, M(B_{4}) = M(A_{h}) = 0.76$$
(3.11)

obtaining:

$$x(1) = \frac{f_{A_h}(x) \times f_{A_h}(y) \times 0.27 + f_{A_l}(x) \times f_{A_h}(y) \times 0.27 + f_{A_l}(x) \times f_{A_l}(y) \times 0.76 + f_{A_h}(x) \times f_{A_l}(y) \times 0.76}{f_{A_h}(x) \times f_{A_h}(y) + f_{A_l}(x) \times f_{A_h}(y) + f_{A_l}(x) \times f_{A_l}(y) + f_{A_l}(x) \times f_{A_l}(y)} = \frac{0.02160000000 + 0.03599999999 + 0.0422222223 + 0.0253333334}{0.022222223 + 0.02533333334} = 0.4141176472$$

$$(3.12)$$

$$y(1) = \frac{f_{A_h}(x) \times f_{A_h}(y) \times 0.76 + f_{A_l}(x) \times f_{A_h}(y) \times 0.27 + f_{A_l}(x) \times f_{A_l}(y) \times 0.27 + f_{A_h}(x) \times f_{A_l}(y) \times 0.76}{f_{A_h}(x) \times f_{A_h}(y) + f_{A_l}(x) \times f_{A_h}(y) + f_{A_l}(x) \times f_{A_l}(y) + f_{A_l}(x) \times f_{A_l}(y)} = \frac{0.0216000000 + 0.0359999999 + 0.0150000000 + 0.0253333334}{0.0800000000 + 0.1333333333 + 0.0555555556 + 0.0333333334} = 0.453749999'$$

$$(3.13)$$

The same procedure is used to obtain x(t+1), y(t+1) as function of x(t), y(t) for t = 1, 2, ...

For computing the state (x(2),y(2)) we have to start with the initial values (x(1), y(1)) = (0.4141176472, 0.453749999') and compute the following *DOF* - *s*

$$\begin{aligned} &DOF\left(\left(0.4141176472\,isA_{h}\right)AND\left(0.4537499999\,isA_{h}\right)\right) = f_{A_{h}}\left(0.4141176472\right) \times \\ &f_{A_{h}}\left(0.4537499999\right) = \frac{0.4141176472-0.4}{0.5} \times \frac{0.4537499999-0.4}{0.5} = 0.003035294142, \\ &DOF(\left(0.4141176472\,isA_{l}\right)AND\left(0.4537499999\,isA_{h}\right)\right) = f_{A_{l}}\left(0.4141176472\right) \times \\ &f_{A_{h}}\left(0.4537499999\right) = \frac{0.7-0.4141176472}{0.6} \times \frac{0.4537499999-0.4}{0.5} = 0.05122058810 \\ &DOF\left(\left(0.4141176472\,isA_{l}\right)AND\left(0.4537499999\,isA_{l}\right)\right) = f_{A_{l}}\left(0.4141176472\right) \times \\ &f_{A_{l}}\left(0.4537499999\right) = \frac{0.7-0.4141176472}{0.6} \times \frac{0.7-0.4537499999}{0.6} = 0.1955514706 \\ &DOF\left(\left(0.4141176472\,isA_{h}\right)AND\left(0.45374999999\,isA_{l}\right)\right) = f_{A_{h}}\left(x\right) \times f_{A_{l}}\left(y\right) \\ &= \frac{0.4141176472-0.4}{0.5} \times \frac{0.7-0.4537499999}{0.6} = 0.01158823541 \end{aligned}$$

In case of nutrients x, the mean values $M(B_i)$ of individual consequences will be replaced by

$$M(B_1) = M(A_l) = 0.27, \ M(B_2) = M(A_l) = 0.27,$$

$$M(B_3) = M(A_h) = 0.76, \ M(B_4) = M(A_h) = 0.76$$

In case of algae y, the mean values $M(B_i)$ of individual consequences will be replaced by

$$M(B_1) = M(A_h) = 0.76, M(B_2) = M(A_l) = 0.27,$$

$$M(B_3) = M(A_l) = 0.27, M(B_4) = M(A_h) = 0.76$$

obtaining:

$$x(2) = \frac{f_{A_{h}}(x) \times f_{A_{h}}(y) \times 0.27 + f_{A_{l}}(x) \times f_{A_{h}}(y) \times 0.27 + f_{A_{l}}(x) \times f_{A_{l}}(y) \times 0.76 + f_{A_{h}}(x) \times f_{A_{l}}(y) \times 0.76}{f_{A_{h}}(x) \times f_{A_{l}}(y) + f_{A_{l}}(x) \times f_{A_{h}}(y) + f_{A_{l}}(x) \times f_{A_{l}}(y) + f_{A_{l}}(y) + f_{A_{l}}(y)$$

https://doi.org/10.29328/journal.ijpra.1001124



$$y(2) = \frac{f_{A_{h}}(x) \times f_{A_{h}}(y) \times 0.76 + f_{A_{l}}(x) \times f_{A_{h}}(y) \times 0.27 + f_{A_{l}}(x) \times f_{A_{l}}(y) \times 0.27 + f_{A_{h}}(x) \times f_{A_{l}}(y) \times 0.76}{f_{A_{h}}(x) \times f_{A_{h}}(y) + f_{A_{l}}(x) \times f_{A_{h}}(y) + f_{A_{l}}(x) \times f_{A_{h}}(y) + f_{A_{l}}(x) \times f_{A_{l}}(y) + f_{A_{h}}(x) \times f_{A_{l}}(y) + f_{A_{h}}(x) \times f_{A_{h}}(y) + f_{A_{h}}(y)$$

For computing the state (x(3), y(3)) we have to start with the initial values (x(2), y(2)) = (0.6582944494, 0.2974125877) and compute the following *DOF* - s

$$\begin{split} &DOF\left(\left(0.6582944494isA_{h}\right)AND\left(0.2974125877\right)isA_{h}\right)\right) = \\ &f_{A_{h}}\left(0.6582944494\right) \times f_{A_{h}}\left(0.2974125877\right)\right) = \frac{0.6582944494 - 0.4}{0.5} \times 0 = 0, \\ &DOF\left(\left(0.6582944494isA_{l}\right)AND\left(0.2974125877isA_{h}\right)\right) = \\ &f_{A_{l}}\left(0.6582944494\right) \times f_{A_{h}}\left(0.2974125877\right) = \frac{0.6582944494 - 0.4}{0.5} \times 0 = 0 \\ &DOF\left(\left(0.6582944494isA_{l}\right)AND\left(0.2974125877isA_{l}\right)\right) = f_{A_{l}}\left(0.6582944494\right) \times \\ &f_{A_{l}}\left(0.2974125877\right) \frac{0.7 - 0.6582944494}{0.6} \times \frac{0.7 - 0.2974125877}{0.6} = 0.04663924915 \\ &DOF\left(\left(0.6582944494isA_{h}\right)AND\left(0.2974125877isA_{l}\right)\right) = f_{A_{h}}\left(0.6582944494\right) \times \\ &DOF\left((0.6582944494isA_{h}\right)AND\left(0.2974125877isA_{l}\right) = f_{A_{h}}\left(0.6582944494\right) \times \\ &DOF\left((0.6582944494isA_{h}\right)AND\left(0.2974125877isA_{l}\right) = f_{A_{h}}\left(0.6582944494\right) \times \\ &DOF\left((0.6582944494isA_{h}\right)AND\left(0.2974125877isA_{l}\right) = f_{A_{h}}\left(0.6582944494\right) \times \\ &DOF\left((0.6582$$

 $f_{A_l}(0.2974125877) = \frac{0.6582944494 - 0.4}{0.5} \times \frac{0.7 - 0.2974125877}{0.6} = 0.01158823541$

For nutrients x using the mean values $M(B_i)$ of individual consequences

$$M(B_1) = M(A_l) = 0.27, \ M(B_2) = M(A_l) = 0.27, M(B_3) = M(A_h) = 0.76, \ M(B_4) = M(A_h) = 0.76$$

The computed value of x(3) is x(3) = 0.75999999999

For algae *y*, using the $M(B_i)$ of individual consequences will be replaced by

$$M(B_1) = M(A_h) = 0.76, \ M(B_2) = M(A_l) = 0.27,$$

$$M(B_3) = M(A_l) = 0.27, \ M(B_4) = M(A_h) = 0.76$$

The computed value of y(3) is y(3) = 0.7018876635

For computing the state (x(4), y(4)) we have to start with the initial values (x(3), y(3)) = (0.7599999999, 0.7018876635) and compute the following *DOF* – *s*

$$DOF((0.7599999999) isA_h)AND (0.7018876635 is A_h)) = f_{A_h}(0.7599999999) \times f_{A_h}(0.7018876635) = 0.1173739235,$$

$$DOF((0.7599999999) isA_l)AND (is A_h)) = f_{A_l}(0.7599999999) \times f_{A_h}(0.7018876635) = 0$$

$$DOF((0.75999999999) isA_l)AND(0.7018876635 isA_l)) = f_{A_l}(0.7599999999) \times f_{A_l}(0.7018876635) = 0$$

$$DOF((0.75999999999) is A_h)AND(0.7018876635 is A_l)) = f_{A_h}(0.7599999999) \times f_{A_l}(0.7018876635) = 0$$
For nutrients x using the mean values $M(B_l)$ of individual consequences
$$M(B_1) = M(A_l) = 0.27, M(B_2) = M(A_l) = 0.27,$$

$$M(B_3) = M(A_h) = 0.76, M(B_4) = M(A_h) = 0.76$$
The computed value of $x(4)$ is $x(4) = 0.2699999999$



For algae *y*, using the $M(B_i)$ of individual consequences will be replaced by

$$M(B_1) = M(A_h) = 0.76, M(B_2) = M(A_l) = 0.27,$$

$$M(B_3) = M(A_l) = 0.27, M(B_4) = M(A_h) = 0.76$$

The computed value of y(4) is y(4) = 0.75999999999

The dynamics of the nutrient evolution and that of the algae evolution during the first four steps are represented in the next Figure 3.1.



For other descriptions, with a system of fuzzy reasoning, of dynamics of real-world phenomena, [4-8].

Conclusion

In this paper, the concept of 'system of fuzzy reasoning' is presented. Basic properties of the concept are underlined. Illustrative examples are given. An example of a model, describing real-world phenomena, using an expert knowledge-based system of fuzzy reasoning is provided.

Contribution

The two authors contributed equally to the realization of this work. All authors have read and agreed to the published version of the manuscript.

Acknowledgment

We acknowledge the Department of Computer Science, namely Prof Dr. Daniela Zaharia, for encouraging this research.

References

- 1. Cojocaru AV, Balint S. The 'human intelligence' linguistic variable is a potential fuzzy computational model for the natural languish expression 'human intelligence. Computing&AI Connect. 2025;2:2025.0015. https://doi.org/Registering%20DOI
- Cojocaru AV, Balint S. What is the true value of fuzzy reasoning in the framework of the 'human intelligence 'linguistic variable? Int J Phys Res Appl. 2025;8(4):065-100. Available from: https://dx.doi.org/10.29328/journal.ijpra.1001117
- Bardossy A, Duckstein L. Fuzzy rule-based modeling with applications to geophysical, biological, and engineering systems. Boca Raton: CRC Press; 1995;256. Available from: https://doi.org/10.1201/9780138755133
- Zimmermann HJ. Fuzzy set theory and its application. 4th ed. Springer Science + Business media; 2001. Available from: https://link.springer.com/ book/10.1007/978-94-010-0646-0
- Dubois D, Prade H. Possibility Theory: An approach to computerized processing of uncertainty. New York: Plenum Press; 1988;268. Available from: https://archive.org/details/possibilitytheor0000dubo
- Yasunobu S, Miyamoto S. Automatic train operation system by predictive fuzzy control. In: Sugeno (ed). Industrial applications of Fuzzy control. North Holland, Amsterdam; 1985;1–18.
- 7. Shingu T, Nishimori E. Fuzzy based automatic focusing system for a compact camera. In: Proceedings of the third IFSA Congress; 1989;436-439.
- Holmblad LP, Ostergaard JJ. Control of cement kiln by fuzzy logic. In: Gupta MM, Sanchez E (eds). Fuzzy Information and Decision Processes. North Holland, Amsterdam; 1982.